



SF-7841

B. E. - IV (Sem. VIII) (Mechanical) Examination
May / June - 2011
Instrumentation & Control

Time : 3 Hours]

[Total Marks : 100

Instructions :

(1)

नीचे दृष्टावेक निशानीवाणी विगतो उत्तरवही पर अवश्य कभवी.
Fillup strictly the details of signs on your answer book.

Name of the Examination :
B. E. - 4 (SEM. 8) (MECHANICAL)

Name of the Subject :
INSTRUMENTATION & CONTROL

Subject Code No. : 7 8 4 1 Section No. (1, 2,.....) : NIL

Seat No. :

Student's Signature

- (2) Attempt all the questions.
- (3) Figures to the right indicate full marks.
- (4) Use of graph paper is allowed.
- (5) Assume suitable data if required.
- (6) Use of Laplace transform table is not allowed.

- 1 (a) Explain following term given below (any five) 5
- (i) What are the fundamental components of Electrical system ?
 - (ii) Define : Peak overshoot
 - (iii) What is a synchro ?
 - (iv) Define : Peak time
 - (v) Write a mathematical expression of Laplace transformation.
 - (vi) Define : Variance
 - (vii) What is control system ?
- (b) Determine the stability of a closed loop control system whose characteristic equation is 5
- $$s^6 + 2s^5 + 8s^4 + 12s^3 + 20s^2 + 16s + 16 = 0$$

- (c) Write short note on any two of the following : 10
- (i) Mathematical model of thermal system
 - (ii) Integral controller
 - (iii) Transfer function
 - (iv) Mathematical model of pneumatic system

- 2 (a) Obtain the inverse of Laplace of : 5

$$F(S) = \frac{3S + 26}{S^2 + 4S + 20}$$

- (b) Obtain the solution of differential equation given below: 5

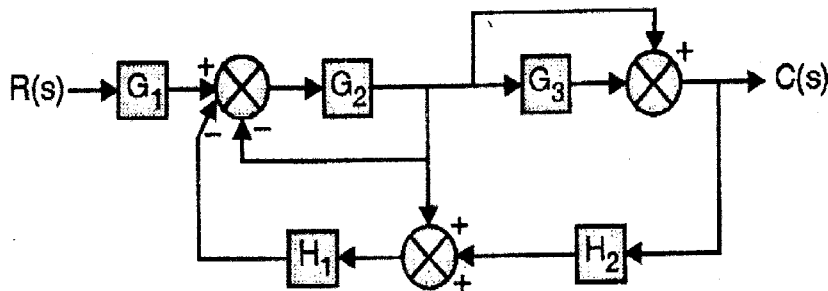
(i) $\frac{d^2x}{dt^2} + 5\frac{dy}{dt} + 6y = 12e^t$; given $y(0+) = 0$ and $y'(0+) = 6$

- (ii) Explain proportional controller 5

OR

- (b) Sketch PID controller. Draw its block diagram and obtain its transfer function. State merits and limitations of the controller. 10

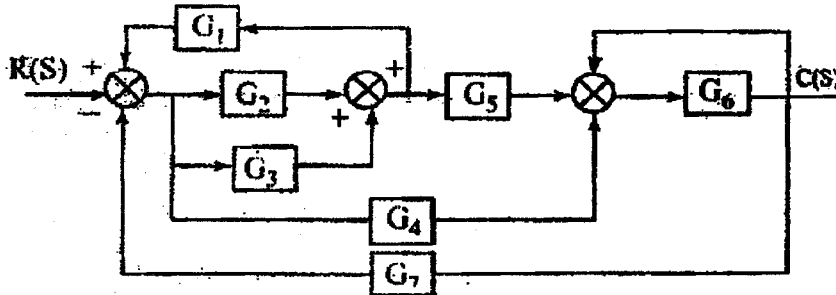
- 3 (a) Using the block diagram techniques, find the closed - loop functions of the following systems. 7



OR

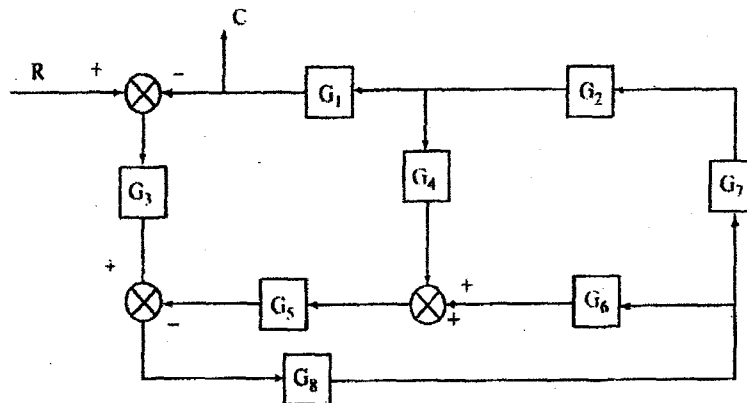
- (a) Using the block diagram techniques, find the closed-loop functions of the following systems.

7



- (b) Construct an equivalent signal flow graph for the block diagram shown in figure and evaluate the transfer function.

8



- 4 (a) Explain given below :
- (i) Difference between primary and secondary transducer
 - (ii) Piezo-electric effect
 - (iii) 1st order instrument
 - (iv) Data acquisition system
 - (v) Active transducer
- (b) Explain major elements and its function of data acquisition and processing system.

5

10

- 5 (a) Explain Capacitive transducer. 5
- (b) A Piezo-electric transducer has a capacitance of 1000pF 10
 and a charge sensitivity of 0.00040 C/m. The connecting
 cable has a capacitance of 300pF while the oscilloscope
 used for readout has a readout input resistance of
 1M Ω with a parallel capacitance of 50 pF.
- (i) What is the sensitivity of the transducer alone ?
- (ii) What is the lowest frequency that can be measured
 with 5% amplitude error by the entire system ?
- (iii) What the high frequency sensitivity of the entire
 system ?
- (iv) What is the value of an external shunt capacitance
 that can be connected in order to extend the range
 of 5% error down to 10Hz ?
- (v) With external capacitance calculated in (d) connected
 in the circuit, what is the system high frequency
 sensitivity ?

- 6 (a) Discuss the importance of data transmission in the 10
 content of modern measurement.

OR

- (a) (i) Explain digital display device. 5
- (ii) Write on successive approximation method. 5
- (b) Explain any two : 10
- (i) Hall Effect transducer
- (ii) Digital transducer
- (iii) LVDT
- (iv) A/D converter.